

# Solvability of an initial-value problem of non-linear implicit fractal differential equation

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**ABSTRACT:** In this paper we study the initial-value problem of the fractal differential equation

$$\frac{dx(t)}{dt^\beta} = f\left(t, \frac{dx(t)}{dt^\alpha}\right), \quad a.e. \quad t \in (0, T], \quad x(0) = x_0.$$

We discuss the existence of at least one solution  $x \in AC[0, T]$ . The Uniqueness of the solution will be proved. The continuous dependence on the initial data  $x_0$  and on the function  $f$  will be analysed. Also, the Hyers - Ulam stability of the problem will be established. Finally, some examples will be given to verify our results.

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## 1. INTRODUCTION

Implicit fractal differential equations represent a fascinating area of study that combines fractal geometry and differential equations. These equations involve fractal-like structures and demonstrate intricate and self-similar patterns (see [2, 11]). They are characterized by their non-linearity and often exhibit complex behaviours, such as chaos and self-replication (see [13, 14]). Differential equations and fractal differential equations have applications in various fields, including physics, biology, and finance, and have garnered significant interest due to their ability to model complex systems with remarkable precision (see [1, 4, 6, 10, 12]).

In this paper we will focus on this initial-value problem of non-linear implicit fractal differential equation.

$$\frac{dx(t)}{dt^\beta} = f\left(t, \frac{dx(t)}{dt^\alpha}\right), \quad a.e. \quad t \in (0, T], \quad x(0) = x_0, \quad (1)$$

where  $\beta, \alpha \in (0, 1)$ , and  $\beta > \alpha$ .

## 2. Existence of solution

Let  $I = [0, T]$  and suppose the following conditions:

(i)  $f: I \times \mathbb{R} \rightarrow \mathbb{R}$  is measurable in  $t \in I$  for any  $x \in \mathbb{R}$  and continuous in  $x \in \mathbb{R}$  for almost all  $t \in I$ .

(ii) There exist a function  $a \in L_1(I)$  such that  $\int_0^T s^{\beta-1} |a(s)| ds \leq M$  and a positive constant  $b$  such that

$$|f(t, x)| \leq a(t) + b|x|, \quad b > 0.$$

$$(iii) \quad b \frac{\beta}{\alpha} T^{\beta-\alpha} < 1$$

**Lemma 1.** The solution of the problem (1), if it exists, then it can be given by the integral equation.

$$x(t) = x_0 + \int_0^t y(s) ds, \quad t \in (0, T], \quad (2)$$

where  $y$  is the solution of the functional equation.

$$y(t) = \beta t^{\beta-1} f\left(t, \frac{1}{\alpha} t^{1-\alpha} y(t)\right). \quad (3)$$

**Proof.** Let  $x$  be a solution of (1), then we have

$$\frac{dx(t)}{dt} \frac{dt}{dt^\beta} = f\left(t, \frac{dx(t)}{dt} \frac{dt}{dt^\alpha}\right),$$

$$\frac{dx(t)}{dt} \frac{1}{\beta t^{\beta-1}} = f\left(t, \frac{1}{\alpha t^{\alpha-1}} \frac{dx(t)}{dt}\right),$$

$$\frac{dx(t)}{dt} = \beta t^{\beta-1} f\left(t, \frac{1}{\alpha t^{\alpha-1}} \frac{dx(t)}{dt}\right).$$

Let  $y(t) = \frac{dx(t)}{dt}$ , we obtain

$$x(t) = x_0 + \int_0^t y(s) ds$$

and

$$y(t) = \beta t^{\beta-1} f\left(t, \frac{1}{\alpha t^{\alpha-1}} y(t)\right).$$

Let  $y$  be a solution of (3), then from (2)

$$\begin{aligned} x(t) &= x_0 + \beta \int_0^t s^{\beta-1} f(s, \frac{1}{\alpha} s^{1-\alpha} y(s)) ds \\ &= x_0 + \beta \int_0^t s^{\beta-1} f(s, \frac{1}{\alpha} s^{1-\alpha} \frac{dx(s)}{ds}) ds. \end{aligned}$$

Thus

$$\begin{aligned} \frac{dx(t)}{dt^\beta} &= \beta \frac{d}{dt^\beta} \int_0^t s^{\beta-1} f(s, \frac{1}{\alpha} s^{1-\alpha} \frac{dx(s)}{ds}) ds \\ &= \beta \frac{dt}{dt^\beta} \frac{d}{dt} \int_0^t s^{\beta-1} f(s, \frac{1}{\alpha} s^{1-\alpha} \frac{dx(s)}{ds}) ds \\ &= \beta \frac{1}{\beta t^{\beta-1}} t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} \frac{dx(t)}{dt}) \\ &= f(t, \frac{dx(t)}{dt^\alpha}), \quad a.e. \quad t \in (0, T]. \end{aligned}$$

Using (2), we get  $x(0) = x_0$ . Which completes the proof.

Now, we have the following existences theorem.

**Theorem 1.** Let the assumptions (i)-(iii) be satisfied, then the functional equation (3) has at least one integrable solution  $y \in L_1(I)$ . Consequently, the initial-value problem (1) has at least one solution  $x \in AC(I)$ .

**Proof.** Let  $Q_r$  be the closed ball

$$Q_r = \{y \in R : \|y\|_{L_1(I)} \leq r\}, \quad r = \frac{\beta M}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}}$$

and the operator  $F$  is defined by

$$Fy(t) = \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)).$$

Now, let  $y \in Q_r$ , then

$$\begin{aligned} |Fy(t)| &= |\beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t))| \\ &\leq \beta t^{\beta-1} |f(t, \frac{1}{\alpha} t^{1-\alpha} y(t))| \\ &\leq \beta t^{\beta-1} (|a(t)| + b | \frac{1}{\alpha} t^{1-\alpha} y(t) |) \\ &\leq \beta t^{\beta-1} |a(t)| + b \frac{\beta}{\alpha} T^{\beta-\alpha} |y(t)| \end{aligned}$$

and

$$\begin{aligned} \int_0^T |Fy(s)| ds &\leq \beta \int_0^T s^{\beta-1} |a(s)| ds + b \frac{\beta}{\alpha} T^{\beta-\alpha} \int_0^T |y(s)| ds \\ &\leq \beta M + b \frac{\beta}{\alpha} T^{\beta-\alpha} \|y\|_{L_1} \\ &\leq \beta M + b \frac{\beta}{\alpha} T^{\beta-\alpha} r, \end{aligned}$$

Thus

$$\|Fy\| \leq \beta M + b \frac{\beta}{\alpha} T^{\beta-\alpha} r = r.$$

This proves that  $F: Q_r \rightarrow Q_r$  and the class of function  $\{Fy\}$  is uniformly bounded in  $Q_r$ .

Now, let  $y \in Q_r$ , then

$$\begin{aligned} \int_0^T |(Fy(s))_h - (Fy(s))| ds &= \int_0^T | \frac{1}{h} \int_t^{t+h} Fy(\theta) d\theta - Fy(s) | ds \\ &= \int_0^T \frac{1}{h} | \int_t^{t+h} (Fy(\theta) - Fy(s)) d\theta | ds \\ &\leq \int_0^T \frac{1}{h} \int_t^{t+h} |Fy(\theta) - Fy(s)| d\theta ds, \end{aligned}$$

Thus

$$\begin{aligned} \|(Fy)_h - (Fy)\|_{L_1} &\leq \int_0^T \frac{1}{h} \int_t^{t+h} | \beta \theta^{\beta-1} f(\theta, \frac{1}{\alpha} \theta^{1-\alpha} y(\theta)) \\ &\quad - \beta s^{\beta-1} f(s, \frac{1}{\alpha} s^{1-\alpha} y(s)) | d\theta ds \end{aligned}$$

Since  $Fy = \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y) \in Q_r \subset L_1(I)$ , it follows that

$$\begin{aligned} \int_0^T \frac{1}{h} \int_t^{t+h} | \beta \theta^{\beta-1} f(\theta, \frac{1}{\alpha} \theta^{1-\alpha} y(\theta)) - \\ \beta s^{\beta-1} f(s, \frac{1}{\alpha} s^{1-\alpha} y(s)) | d\theta ds \rightarrow 0, \quad as \quad h \rightarrow 0. \end{aligned}$$

Then  $(Fy)_h \rightarrow (Fy)$  uniformly in  $L_1(I)$ . Thus the class  $\{Fy\}$ ,  $y \in Q_r$  is relatively compact [9]. Hence  $F$  is compact operator [3].

Now, let  $\{y_n\} \subset Q_r$ , and  $y_n \rightarrow y$ , then

$$Fy_n(t) = \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y_n(t))$$

and

$$\begin{aligned} \lim_{n \rightarrow \infty} Fy_n(t) &= \beta t^{\beta-1} \lim_{n \rightarrow \infty} f(t, \frac{1}{\alpha} t^{1-\alpha} y_n(t)) \\ &= \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} \lim_{n \rightarrow \infty} y_n(t)) \\ &= \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) \\ &= Fy(t). \end{aligned}$$

This means that  $Fy_n(t) \rightarrow Fy(t)$ . Hence the operator  $F$  is continuous.

Now, by Schauder fixed point Theorem [8] there exists at least one solution  $y \in Q_r \subset L_1(I)$  of the functional equation (3). Consequently, there exists at least one solution  $x \in AC(I)$  of the problem (1).

### 3. Uniqueness of the solution

Now, consider the following assumption:

(i)\*  $f: I \times R \rightarrow R$  is measurable in  $t \in I$  for every  $x \in R$  and satisfies the Lipschitz condition

$$|f(t, x) - f(t, y)| \leq b |x - y|, \quad b > 0, \quad (4)$$

where  $|f(t, 0)| = a(t)$  is bounded.

**Remark 1.** From (4) we obtain

$$\begin{aligned} |f(t, x)| - |f(t, 0)| &\leq |f(t, x) - f(t, 0)| \leq b |x| \\ |f(t, x)| &\leq a(t) + b |x|, \quad b > 0. \end{aligned}$$

**Theorem 2.** Let the assumption (i)\* be satisfied. If  $b \frac{\beta}{\alpha} T^{\beta-\alpha} < 1$ , then the solution  $y \in L_1(I)$  of the functional equation (3) is unique. Consequently, the solution  $x \in AC(I)$  of the problem (1) is unique.

**Proof.** From remark 1, all assumptions of Theorem 1 are satisfied and the solution of the functional equation (3) exists.

Now, let  $y, z$  be two solutions of equation (3), then

$$\begin{aligned} |y(t) - z(t)| &= | \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} z(t)) | \\ &= \beta t^{\beta-1} | f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - f(t, \frac{1}{\alpha} t^{1-\alpha} z(t)) | \\ &\leq \beta t^{\beta-1} b | \frac{1}{\alpha} t^{1-\alpha} y(t) - \frac{1}{\alpha} t^{1-\alpha} z(t) | \\ &\leq b \frac{\beta}{\alpha} T^{\beta-\alpha} |y(t) - z(t)| \end{aligned}$$

and

$$\begin{aligned} \int_0^T |y(s) - z(s)| ds &\leq b \frac{\beta}{\alpha} T^{\beta-\alpha} \int_0^T |y(s) - z(s)| ds \\ \|y - z\|_{L_1} &\leq b \frac{\beta}{\alpha} T^{\beta-\alpha} \|y - z\|_{L_1}. \end{aligned}$$

Hence,

$$\|y - z\|_{L_1} (1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}) \leq 0.$$

Then  $y = z$ , this implies that the solution of the functional equation (3) is unique. Consequently, the solution of the problem (1) is unique.

### 4. Continuous dependence

**Definition 1.** [7] The solution  $x$  of the problem (1) depends continuously on the initial data  $x_0$  and on the function  $f$ , if  $\forall \epsilon > 0, \exists \delta > 0$  s.t.

$$\max \{ |x_0 - x_0^*|, |f - f^*| \} < \delta,$$

implies

$$\|x - x^*\| < \epsilon,$$

where  $x^*$  is the unique solution of the problem

$$\frac{dx^*(t)}{dt^\beta} = f^*(t, \frac{dx^*(t)}{dt^\alpha}), \quad a.e. \quad t \in (0, T], \quad x(0) = x_0^*, \quad (5)$$

where  $\beta, \alpha \in (0, 1)$ , and  $\beta > \alpha$ .

**Theorem 3.** Let the assumptions of Theorem 2 be satisfied, then the solution of the problem (1) depends continuously on the initial value  $x_0$  and on the function  $f$ .

**Proof.** Let  $x, x^*$  be the two solutions of (1) and (5) respectively, then

$$\begin{aligned} |y(t) - y^*(t)| &= \\ &| \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - \beta t^{\beta-1} f^*(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) | \\ &= \beta t^{\beta-1} | f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - f^*(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) | \\ &= \beta t^{\beta-1} | f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - f(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) \\ &\quad + f(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) - f^*(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) | \\ &\leq \beta t^{\beta-1} | f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - f(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) | \\ &+ \beta t^{\beta-1} | f(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) - f^*(t, \frac{1}{\alpha} t^{1-\alpha} y^*(t)) | \\ &\leq \beta t^{\beta-1} b | \frac{1}{\alpha} t^{1-\alpha} y(t) - \frac{1}{\alpha} t^{1-\alpha} y^*(t) | + \beta t^{\beta-1} \delta \\ &\leq \beta t^{\beta-1} b \frac{1}{\alpha} t^{1-\alpha} |y(t) - y^*(t)| + \beta t^{\beta-1} \delta \\ &\leq b \frac{\beta}{\alpha} T^{\beta-\alpha} |y(t) - y^*(t)| + \beta t^{\beta-1} \delta \\ &(1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}) |y(t) - y^*(t)| \leq \beta t^{\beta-1} \delta \\ &|y(t) - y^*(t)| \leq \frac{\beta t^{\beta-1} \delta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}}. \end{aligned}$$

Hence

$$\int_0^T |y(s) - y^*(s)| ds \leq \frac{T^\beta \delta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}}.$$

Now,

$$\begin{aligned} |x(t) - x^*(t)| &= |x_0 + \int_0^t y(s) ds - x_0^* - \int_0^t y^*(s) ds| \\ &= |(x_0 - x_0^*) + \int_0^t (y(s) - y^*(s)) ds| \\ &\leq |x_0 - x_0^*| + \int_0^t |y(s) - y^*(s)| ds \\ &\leq \delta + \frac{T^\beta \delta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}} \\ \|x - x^*\| &\leq \delta + \frac{T^\beta \delta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}} = \epsilon. \end{aligned}$$

Which completes the proof.

### 5. Hyers-Ulam stability

**Definition 2.** Let the solution of the problem (1) be exists uniquely, then the problem (1) is Hyers-Ulam stable [5] if  $\forall \epsilon > 0, \exists \delta > 0$  such that for any  $\delta$ -approximate solution  $x_s$  of problem (1) satisfying

$$| \frac{dx_s(t)}{dt^\beta} - f(t, \frac{dx_s(t)}{dt^\alpha}) | < \delta,$$

implies

$$\|x - x_s\| < \epsilon.$$

**Theorem 4.** Let the assumption of Theorem 2 be satisfied. Then the problem (1) is Hyers-Ulam stable.

**Proof.** Let

$$\begin{aligned} &| \frac{dx_s(t)}{dt^\beta} - f(t, \frac{dx_s(t)}{dt^\alpha}) | < \delta \\ &-\delta < \frac{dx_s(t)}{dt^\beta} - f(t, \frac{dx_s(t)}{dt^\alpha}) < \delta \\ &-\delta < \frac{1}{\beta t^{\beta-1}} \frac{dx_s(t)}{dt} - f(t, \frac{1}{\alpha} t^{1-\alpha} \frac{dx_s(t)}{dt}) < \delta \\ &-\delta \beta t^{\beta-1} < \frac{dx_s(t)}{dt} - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} \frac{dx_s(t)}{dt}) < \delta \beta t^{\beta-1} \end{aligned}$$

Let  $y_s(t) = \frac{dx_s(t)}{dt}$ ,

$$\begin{aligned} -\delta \beta t^{\beta-1} &< y_s(t) - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y_s(t)) < \delta \beta t^{\beta-1} \\ |y_s(t) - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y_s(t))| &< \delta \beta t^{\beta-1} \end{aligned}$$

Then

$$\begin{aligned} |y(t) - y_s(t)| &= | \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - y_s(t) | \\ &= | \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - (y_s(t) - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y_s(t))) \\ &\quad - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y_s(t)) | \\ &\leq \beta t^{\beta-1} | f(t, \frac{1}{\alpha} t^{1-\alpha} y(t)) - f(t, \frac{1}{\alpha} t^{1-\alpha} y_s(t)) | \\ &\quad + | y_s(t) - \beta t^{\beta-1} f(t, \frac{1}{\alpha} t^{1-\alpha} y_s(t)) | \\ &\leq \beta t^{\beta-1} b | \frac{1}{\alpha} t^{1-\alpha} y(t) - \frac{1}{\alpha} t^{1-\alpha} y_s(t) | + \delta \beta t^{\beta-1} \\ &\leq b \frac{\beta}{\alpha} T^{\beta-\alpha} |y(t) - y_s(t)| + \delta \beta t^{\beta-1} \\ &\leq \frac{\delta \beta t^{\beta-1}}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}}. \end{aligned}$$

Thus

$$\int_0^T |y(\theta) - y_s(\theta)| d\theta \leq \frac{\delta T^\beta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}}.$$

Now,

$$\begin{aligned} |x(t) - x_s(t)| &= |x_0 + \int_0^t y(\theta) d\theta - x_0 - \int_0^t y_s(\theta) d\theta| \\ &= | \int_0^t (y(\theta) - y_s(\theta)) d\theta | \\ &\leq \int_0^T |y(\theta) - y_s(\theta)| d\theta \\ &\leq \frac{\delta T^\beta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}} \\ \|x - x_s\| &\leq \frac{\delta T^\beta}{1 - b \frac{\beta}{\alpha} T^{\beta-\alpha}} = \epsilon. \end{aligned}$$

Which completes the proof.

## 6. Examples

**Example 1.** Consider the following initial-value problem of the fractal differential equation

$$\frac{dx(t)}{dt^\beta} = 2t + \frac{1}{5} \frac{\frac{dx(t)}{dt^\alpha}}{1 + \left| \frac{dx(t)}{dt^\alpha} \right|}, \quad a.e. \quad t \in (0,1], \quad x(0) = \frac{1}{2}. \quad (6)$$

Then

$$f(t, x) = 2t + \frac{1}{5} \frac{x(t)}{1 + |x(t)|},$$

where  $a(t) = 2t \in L1(I)$ ,  $\beta = \frac{1}{2}$ ,  $\alpha = \frac{1}{3}$  and  $b = \frac{1}{5} > 0$  such that

$$\int_0^1 s^{\beta-1} |a(s)| ds = \frac{4}{3} \quad \text{and} \quad b \frac{\beta}{\alpha} T^{\beta-\alpha} = \frac{3}{10} < 1.$$

We can show that all conditions of Theorem 2 are satisfied. Then, the initial-value problem (6) has a unique solution.

**Example 2.** Consider the following initial-value problem of the fractal differential equation

$$\frac{dx(t)}{dt^\beta} = \frac{1}{2} t^{1-\beta} + \frac{1}{3} \frac{\frac{dx(t)}{dt^\alpha}}{1 + \sin^2 t}, \quad a.e. \quad t \in (0,2], \quad x(0) = \frac{1}{4}. \quad (7)$$

Then

$$f(t, x) = \frac{1}{2} t^{1-\beta} + \frac{1}{3} \frac{x(t)}{1 + \sin^2 t},$$

where  $a(t) = \frac{1}{2} t^{1-\beta} \in L1(I)$ ,  $\beta = \frac{1}{4}$ ,  $\alpha = \frac{1}{5}$  and  $b = \frac{1}{3} > 0$  such that

$$\int_0^2 s^{\beta-1} |a(s)| ds = 1 \quad \text{and} \quad b \frac{\beta}{\alpha} T^{\beta-\alpha} = 0.43 < 1.$$

We can show that all conditions of Theorem 2 are satisfied. Then, the initial-value problem (7) has a unique solution.

## 7. Conclusions

This research paper focuses on investigate the existence of solutions for the fractal differential problem (1) and properties associated with these solutions. Firstly, we examined the equivalence between the problem (1) and functional equation (3), then we studied the existence of at least one solution  $x \in AC(I)$  of (1) by applying Schauder's fixed point theorem. Furthermore, we established sufficient conditions to ensure the uniqueness of the solution and its continuous dependence on the initial data  $x_0$  and on the function  $f$ . We studied the Hyers-Ulam stability of the problem (1). Finally, some examples have been introduced to illustrate our results.

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